

On-Road Measurement of Automotive Particle Emission Factors by Ultraviolet Lidar and Transmissometer

Hans Moosmüller, Claudio Mazzoleni, Peter W. Barber, Hampden D. Kuhns, Robert E. Keislar, and John G. Watson

Desert Research Institute, University of Nevada System, 2215 Raggio Pky., Reno, NV, 89512

1. Introduction

DRI has developed a remote sensing method for measuring particulate matter (PM) emissions from on-road, in-use, spark ignition and diesel vehicles. Remote sensing of gaseous pollutants in vehicle exhaust is a well-established, economical way to determine on-road emissions for thousands of vehicles per day.

2. Vehicle emission factors (EF) are calculated from CO₂ and PM column contents, as grams of PM emitted per kilograms of fuel consumed.

Assumptions:

•Spherical particle shape

-Density: 1.25 g cm⁻³ -Index of Refraction: Organic Carbon m = 1.5Elemental Carbon m = 1.5 - i0.5

•Particle composition

-Solid OC for spark ignition -Layered sphere with EC core and OC shell for Diesel •Mass size distributions approximated as lognormal: -mass median diameter 0.15 µm -geometric standard deviation 1.5 µm

•UV Transmissivity near 1

•Fuel Composition:

- Gasoline C_nH_{1.825n}

- Diesel C_nH_{2n}

Measurements:

•PM UV backscattering

- •PM UV transmission
- •CO₂ column mass density ρ_{CO2}
- •Lidar calibration with CO₂ and HEPA filtered air

Mass Backscattering Efficiencies

Theoretically calculated from the assumptions: •Spark ignition: $E_{bscat} = 0.16 \text{ m}^2/\text{g}\cdot\text{sr}$ •Diesel: $E_{bscat} = 0.08 \text{ m}^2/\text{g}\cdot\text{sr}$

Mass Extinction Efficiencies

Theoretically calculated from the assumptions: •Spark ignition: $E_{ext} = 10 \text{ m}^2/\text{g}$ •Diesel: $E_{ext} = 13 \text{ m}^2/\text{g}$

EF Computation:

•PM mass density column density from backscattering: $\rho_{PM} = (Exhaust Backscattering) / E_{bscat}$

- •PM mass density column density from transmission: $\rho_{PM} = (Exhaust Optical Depth) / E_{ext}$
- •Emission factors:

 $EF_{PM} = (CMF_{fuel}/CMF_{CO2})(\rho_{PM}/\rho_{CO2})$ [grams_{PM}/kg_{fuel}]

Where CMF = Carbon mass fraction

The DRI Vehicle Emissions Remote Sensing System (VERSS) combines a 266-nm ultraviolet lidar and transmissometer with a commercial remote sensing device (RSD) to measure both particulate matter and gaseous pollutants in the exhaust of passing vehicles. The Idar and transmissometer ultraviolet wavelength achieves greater sensitivity to sub-micrometer particles, where the greatest mass fraction has been reported. The VERSS system integrates the lidar backscatter with infrared column mass density CO₂ measurements to estimate fuel-based PM emissions. Carbon monoxide (CO), nitric oxide (N0), and hydrocarbons (HC) are measured by the collocated gaseous remote sensing.

3. UV Lidar and Transmissometer





Main unit



Ancillary measurement of speed and acceleration and the acquisition of a picture of the rear plate of each vehicle permits stratification of the vehicle emissions by model year, fuel type, vehicle type and vehicle specific power. Example data shown here are from a large field experiment conducted in Las Vegas, NV during spring and summer 2001 and 2002. The data analysis revealed that the dirtiest 10% of the entire measured mobile fleet (14815 valid lidar measurement) was responsible for more than 80% of the total PM emitted.

Retro unit



& 3.9 mm reference)



An example of a Diesel vehicle (ISUZU, model year 2000, CO EF=1.3 g_{CO}/kg_{fuel} , HC EF=2.5 g_{HC}/kg_{fuel} , NO EF=20 g_{NO}/kg_{fuel}) is presented below. Panel (a): time evolution of PM and CO₂ column mass density, panel (b): linear regression. The slope between the PM column mass

density and the consumed fuel column mass density corresponds to the emission factor: $PM EF=1.47 g_{PM}/kg_{fuel}$



Table: Average PM emission factors for Diesel and spark ignition vehicles.

Year	Engine	Average [g _{PM} /kg _{Fuel}]	Standard Error [g _{PM} /kg _{Fuel}]	# Vehicles
2001	Spark ignition	0.070	0.007	6047
	Diesel	2.1	0.35	65
2002	Spark ignition	0.047	0.004	8768
	Diesel	1.3	0.2	191



Plot of PM emission factors for spark ignition vehicle versus age.

5. References

- l. Barber, P. W.; Moosmüller, H.; Keislar, R. E.; Kuhns, H. D.; Mazzoleni, C.; Watson, J. G. "On-Road Measurement of Automotive Particle Emissions by Ultraviolet Lidar and Transmi Theory", Appl. Opt. 2003, submitted.
- 2. Moosmüller, H.; Mazzoleni C.; Keislar, R. E.; Barber, P. W.; Kuhns, H. D.; Watson, J. G. "On-Road Measurement of Automotive Particle Emissions by Ultraviolet Lidar and Transmissometer Instrument', ES&T 2003, published on WWW, to be published in print on Nov. 1, 2003.
- 3. Kuhns, H. D.; Mazzoleni, C.; Moosmüller, H.; Nicolic, D.; Keislar, R. E.; Barber, P. W.; Li, Z.; Etyemezian, V.; Watson, J. G. "Remote Sensing of PM, NO, CO, and HCEemission Factors for On-Road Gasoline and Diesel Engine Vehicles in Las Vegas, NV", Sci. Total. Environ. 2003, in press.
- 4. Mazzoleni, C.; Kuhns, H. D.; Moosmüller, H.; Keislar, R. E.; Barber, P. W.; Robinson, N. F.; Watson, J. G.; Nicolic, D. "Comparison of On-Road Vehicle Particulate Matter and Gaseous Emission Distributions in Las Vegas, NV with Other Areas", JAWMA 2003, submitted.
- 5. Mazzoleni, C.; Moosmüller, H.; Kuhns, H. D.; Keislar, R. E.; Barber, P. W.; Watson, J. G. "Effectiveness of Inspection and Maintenance Programs for Estimating Real World Emissions", JAWMA 2003, submitted.

